



### Product description for ED1608 generic Sigfox/LoRa Module

The ED1608 Sigfox/LoRa Module is developed as a general purpose module that is able to integrate functionality for various applications and communicate with the widely available Low Power Wide Area Networks (LPWAN) SigFox and LoRa.

Time to market is very important at this moment in the LPWAN market segment. The ED1608 module is developed to enable customers to be on the market in a matter of weeks. For rapid prototyping and proof of concept use the ED1608 will be kept on stock in two versions:

The “Full” version and the “Basic” version. For roll-out and larger volumes we can produce “off the shelf” any combination in between.

This works as follows:

Since the PCB size is dictated by the antennas and batteries, there is a lot of space available for other sensors. To decrease the time to market and avoid the risks associated with the development of new hardware and firmware the ED1608-Full version is designed and tested with as many sensors and circuits as we could place on the PCB. Once an application is developed and tested on the ED1608-Full version the ED1608 can be equipped with only the necessary circuits and sensors without the need to develop new hardware, firmware and application software or get new certifications.

The “Basic” version is the most used configuration for tracking purposes. It has GPS, LPWAN radio and an accelerometer, but all other sensors and circuits are not mounted. This reduces the unit price.

The ED1608 is the successor of the ED1600 which is in production since April 2014. The redesign enabled us to improve both on pricing and functionality. It is also smaller and more power efficient than the ED1600.

The housing is available in several configurations.

- 1) Smallest version for a ED1608 board and 1 single cell battery
- 2) Extended bottom for 4-cell battery pack
- 3) Extended bottom for 4-cell battery pack and up to three cable glands
- 4) All above can be fitted with magnet mounting (4 super magnets).

When a project is started and the basic version is not sufficient the full version is recommended for proof of concept or small series. If volumes of 500 or more are required we can produce the units with an application specific set of sensors and circuits to optimise unit prices.

Please contact us on [info@1M2M.eu](mailto:info@1M2M.eu) for pricing of volumes of more than 500 pieces.



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## Product feature overview

### **The full version has these on-board sensors and interfaces:**

- One 868/915 MHz radio for short range wireless sensor networks,
- One 868/915 MHz LoRa and Sigfox enabled LPWAN radio (bidirectional)
- One GPS/Glonass receiver, simultaneously tracking GPS and Glonass at -166 dBm.
- Supply voltage can be anywhere between 3.0 Volt and 5.0 Volt (3.6V nominal) which allows to fully use the capacity a Li-SOCI2 battery, but also allows for a 5V power source
- One switchable 5V power output (200mA max) for external sensors and servos, even on a 3.0V power supply
- One universal 2 channel bidirectional digital 5V sensor/actuator interface or COM port, IIC, etc.
- two combined analog inputs, range 0..5V, with 5mV resolution and/or open collector digital outputs (5V/1A)
- two LED's for diagnose/feedback
- a 3D magnetometer
- a 3D accelerometer
- a high accuracy temperature/RHD sensor
- a barometer (resolution 30cm air pressure)
- a 1wire interface for the widely used DS18B20 1Wire temperature sensor
- a 64 Kbyte nonvolatile memory for data logging or OTA firmware updates
- A 10 pin expansion connector for external sensors and actuators or wired communication.

### **All radio antennas are on the PCB.**

- A 868/915 MHz metal strip antenna for LPWAN and 868 radio. Optionally this antenna can be replaced by a SMA connector to allow for an external antenna.
- A GPS/Glonass 25x25 patch antenna for geolocation reception.



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### Product feature details

The universal 5V power supply and the 5V sensor interface is a way to support as many external sensors as possible with one simple circuit. When enabled it can source a 5V external device with a maximum of 100mA, and supports 2 bidirectional 5V I/O lines. These lines can be used as a TTL-UART (serial), IIC interface, or simple digital I/O, to control for example a mechanical servo drive, LED's, iButton and many more devices that use 5V DC power to operate. Of course there are only 2 pins, so if an interface type needs 2 pins you cannot use another interface in parallel. It is however possible to have one pin as serial TX and the other as servo control or generic I/O.

The **analog inputs** are combined with open drain digital outputs. The default input sensitivity is 5V full scale, when used as outputs they can sink up to 1A to ground. The inputs and outputs can be combined, reading analog voltage when the output is in the "Off" state. This enables for "load connected" detection. Impedance for analog input is 338 kOhm.

The **magnetometer** is also called compass, but without calibration it cannot really be used as a compass. It can be used however to detect changes in earth magnetic field lines or to detect magnetic fields from permanent magnets or AC power lines. Depending on the type and interval of measurements the power consumption can be as low as 10uA so it is possible to keep it "Always On" on a battery.

The **accelerometer** can be used to detect vibration, motion and to see the orientation in the earth's gravitation field. Depending on the type and interval of measurements the power consumption can be as low as 10uA so it is possible to keep it "Always On" on a battery. The temperature/humidity is a high precision sensor that can be used in applications like weather stations or HACCP related applications.

The **temperature sensor** has a resolution of 0.04 degrees Celsius and a accuracy of  $\pm 0.4$  degrees Celsius. The humidity sensor has a resolution of 0.025 %RH and a tolerance of  $\pm 4.0$  %RH (max. 0-80%). This sensor is on the PCB itself, so it cannot be used when the PCB is in a waterproof enclosure. Because the PCB uses very little power, self heating is not a problem, but response time can be quicker when an external sensor is used.

The **barometer** is also a high precision sensor, it has a resolution of 30 cm air pressure. Range is 50 to 110kPa, absolute accuracy  $\pm 0.4$ kPa, resolution  $\pm 0.05$ kPa. Please consider that pressures changes as a result of wind and movement can be much larger than the static pressure as a result of height. Changes in atmospheric pressure are also much larger than pressure changes as a result of height.

The optional **GPS/Glonass** receiver including patch antenna is a very sensitive receiver that combines GPS as well as Glonass satellites to get an optimal position fix.



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Both systems are used simultaneously which results in a very secure and accurate position. This receiver can be a serious power consumer if constantly enabled at full speed. It has however a lot of power saving modes, which will be optimised for a specific application.

The **1Wire interface** consist of 2 wires that can be directly connected to the widely available DS18B20 sensor. We recommend to power the sensor via pin 3 of the 10 pin expansion connector. The sensors can also be used in parasite power mode, but this may lead to erroneous reading. In Parasite Power mode, the +V wire is connected to the ground.

Up to 5 sensors can be used in parallel.

The **non-volatile memory** is for data logging or can be used to store new firmware images that can be downloaded either over the air or by the 5V serial interface. When not used for firmware images the memory is available for storing application data.

The **power regulator system** is designed to make all required voltages from one power source as efficient as possible. The power supply can be anywhere between 2.0 V and 5.0 V, even when the radio or digital I/O needs 3.3 V or 5 V. This allows the device to use the full capacity of a LiPo or Li-SOCl<sub>2</sub> battery. The circuits are optimised for use of primary batteries, but most rechargeable batteries or a 5V power source like USB can be used as well.

### About batteries, power use and autonomy

There are many types of batteries available, but there are 2 main groups: Primary and Rechargeable.

The most important difference (apart from the ability to recharge of course) is the self discharge current. For primary batteries this can be as low as 1% per year.

For rechargeable batteries it is much higher. Lithium Polymer cells experience a self-discharge rate of approximately 5% per month, compared with over 30% per month and 20% per month in NiHM batteries and NiCd batteries respectively.

Depending on the (interval of) use of GPS the ED1608 consumes between 6.7 mWh/day (4 fixes + 4 transmissions a day) and 100 mWh (90 minutes active GPS+120 transmissions a day)

These numbers are theoretical, based on prototypes and optimal radio conditions.

For GPS it takes less time to get a first fix when conditions are good, and the LPWAN can switch to higher bitrates when it is closer to the network so it can reduce the power consuming radio-on time.

The standard battery capacity for a basic version is 8.800 mAh at 3.6V (@20°C).

When 2 fixes + transmissions a day are sufficient a primary battery of 8.800 mAh will last more than 5 years (@ 20°C).

At 52 mWh (90 minutes active GPS+120 transmissions) per day the battery will last for a little more than 1 year.

That is why we advise to use primary batteries.

When using rechargeable batteries with a self discharge of 5% per month about 50% of the capacity will be lost after 1 year, when using rechargeable batteries with a self

discharge of 20% a month there is only 6% capacity remaining after one year. This is even without any load...

We supply four types of Li-SOCl<sub>2</sub> primary battery packs.

- 2.200mAh, size: 52x16x15mm
- 8.800mAh, size: 52 x 61x15mm
- 18.000mAh, size: 52 x 52 x 26 mm
- 38.000 mAh, size: 63 x 67 x 33 mm

At this moment two types of enclosure are available that were developed for container tracking use. They support a 8.800 mAh battery pack which supports GPS/ Glonass use for many months depending on the active profile.

For applications without GPS a much smaller battery can be used, and as a result of that a much smaller enclosure.

On request we can customise and white label the enclosure.

Please email to [info@1M2M.eu](mailto:info@1M2M.eu) for further information.

### Expansion connector

For connecting external sensors and circuits there is a 10 pin expansion connector available. Depending on the enclosure and application one out of 3 possible types is mounted.

1. a straight angle connector type
2. a right angle connector type
3. a very low profile right angle connector type



The first two connector types use this female connector  
Manufacturer: Hirose Electric, Part number: DF13-10S-1.25C  
Depending on the application 2 or more wires can be inserted on the locations that are used

The low profile connector type uses this female connector:  
Manufacturer: Molex, Part number: 5040511001  
Depending on the application 2 or more wires can be inserted on the locations that are used.



Pin	Function	Explanation
1	Ground	Reference for all inputs, outputs and power
2	VBattery	Battery voltage 2.5 to 5.0 Volt, directly connected to the internal battery (if present). If not present this pin can be used to power the module
3	VLogic	Internal power supply voltage output. Depending on the power mode it can be 2.0V, 2.2V or 3.3V. <b>It is not allowed to connect anything to this pin except for circuits approved by 1M2M.</b>
4	Ground	Reference for all inputs, outputs and power
5	I/O switched 5V	Power output for 5V sensors or interfaces It is switched off in low power modes and can source 100mA max. Also powers DIO1 and DIO2 level converters and external hardware
6	DIO1/Rx/SDA	Generic digital IO. Can be used as serial port, IIC port or digital input or output.
7	DIO2/Tx/SCL	Generic digital IO. Can be used as serial port, IIC port or digital input or output.
8	AnIn1/Out1	Digital power output. When activated it can sink 1000 mA. When not activated it is also an analog input. Range 0..5VDC. Impedance is 338 KOhm to ground in this mode. Maximum voltage is -0.2 VDC to +5 VDC.
9	AnIn2/Out2	Same as AnIn1/Out1
10	Ground	Reference for all inputs, outputs and power

**Before connecting any circuits to this connector it is strongly advised to get support and approval from 1M2M. Please email at [info@1m2m.eu](mailto:info@1m2m.eu)  
Any damage caused by non approved circuits voids warranty !**

For advise or additional information please contact us on [info@1m2m.eu](mailto:info@1m2m.eu)

The tracker module enclosures with 8.800 mAh battery pack:  
Size: 31/35 by 81/70 by 74mm



The tracker module enclosures with 2.200 mAh battery pack:  
Size: 16/20 by 81/70 by 74mm (ex magnets)





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### ED1608 Device options

	Full	Basic	Radio-Only
Accelerometer	YES	YES	NO
Battery	YES	YES	YES
Gauss-Detector	YES	NO	NO
GPS Receiver	YES	YES	NO
10-P Connector	YES	NO	YES
IPEX/U.FL (external antenna)	NO	NO	NO
LED RED	YES	YES	YES
LED GREEN	YES	NO	NO
LED ORANGE	YES	NO	NO
3-P Connector (Battery)	YES	YES	YES
Option 5V +5V I/O	YES	NO	YES
Barometer	YES	NO	NO
Option Flash	YES	NO	NO
Magnetometer	YES	NO	NO
OneWire	YES	YES	YES
OneWire Sensor	NO	NO	NO
Power I/O	YES	NO	YES
Temperature/Rhd	YES	NO	NO
Bluetooth	NO	NO	NO
Processor	YES	YES	YES
SIGFOX/LoRa	YES	YES	YES

For quotes or advise on different sets of options or external sensors or circuitry please contact [info@1M2M.eu](mailto:info@1M2M.eu)

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